

WEST Search History

DATE: Wednesday, August 06, 2008

<u>Hide?</u>	<u>Set Name</u>	<u>Query</u>	<u>Hit Count</u>
		<i>DB=PGPB,USPT; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L42	((("20040236467" "20030125839" "20030114960")!.PN.) .PGPB. ((("6377014" "6301524" "6289265" "6243623" "5838130" "5758734" "5404086" "5402050")!.PN.) .USPT.	11
		<i>DB=USPT; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L41	((("6920374" "5841258" "5404086")!.PN.) .USPT.	3
		<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L40	ground and contact and L38	22
<input type="checkbox"/>	L39	groung and contact and L38	0
<input type="checkbox"/>	L38	sensor and L37	30
<input type="checkbox"/>	L37	axis and L36	30
<input type="checkbox"/>	L36	soles and L35	30
<input type="checkbox"/>	L35	foot and L34	34
<input type="checkbox"/>	L34	L33 and coordinate	34
<input type="checkbox"/>	L33	position and orientation and L32	39
<input type="checkbox"/>	L32	(L4 or L5) and L31	79
<input type="checkbox"/>	L31	landed and landing and foot and robot\$6	144
<input type="checkbox"/>	L30	landed and landing and foot and footstep and robot\$6	6
<input type="checkbox"/>	L29	landed and landing and foot and footstep and (L4 or L5)	3
<input type="checkbox"/>	L28	landded and landing and foot and footstep and (L4 or L5)	0
<input type="checkbox"/>	L27	landded and landing and foot and footstep and L18	0
<input type="checkbox"/>	L26	landded and landing and foot and L25	0
<input type="checkbox"/>	L25	posture and L24	48
<input type="checkbox"/>	L24	gravity and coordinate and L23	49
<input type="checkbox"/>	L23	estimat\$3 and position and L22	57

<input type="checkbox"/>	L22	dynamics same model and L19	69
<input type="checkbox"/>	L21	dyanamics and L19	0
<input type="checkbox"/>	L20	dyanamics same model and L19	0
<input type="checkbox"/>	L19	L17 and L18	171
<input type="checkbox"/>	L18	movement or trajectory and L17	2589534
<input type="checkbox"/>	L17	floor and zmp and L4	180
<input type="checkbox"/>	L16	floor and zmp and L15	0
<input type="checkbox"/>	L15	(5024920 5173382 5490103 5557564 5901829 6201488 6521838 6518503 6695663 6592418 5733819 6027554 6663326 6694847 6685863 4252414 4588518 4561746 4719331 5118090 5434926 5419740 5558196 5527940 5716481).pn.	47
<input type="checkbox"/>	L14	motion pattern and L12	2
<input type="checkbox"/>	L13	motion pattern and stor\$3 and L12	0
<input type="checkbox"/>	L12	freedom and L11	5
<input type="checkbox"/>	L11	L9 and L10	6
<input type="checkbox"/>	L10	L9 and gait or gate	1213679
<input type="checkbox"/>	L9	('6580969' 'l'6493606' 'l'6463356' 'l'6289265' 'l'6243623' 'l'5872893' 'l'5841258' 'l'5838130' 'l'5594644' 'l'EP 1136193A' 'l'EP 1103451A')!.ABPN1, NRPN,PN,TBAN,WKU.	18
<input type="checkbox"/>	L8	('20030019671' 'l'20020138359' 'l'6591923' 'l'6458011')!.ABPN1,NRPN,PN, TBAN,WKU.	7
<input type="checkbox"/>	L7	(legged robot or pet robot or humanoid near10 robot) motion and pattern	13
<input type="checkbox"/>	L6	(legged robot or pet robot or humanoid near10 robot) motion and pattern and L5	0
<input type="checkbox"/>	L5	(6252544 6493606 6243623 6289265 5673367 5355064 5455497 5325031 5357433 5594644 6580969 6718231 5504841 5842533 4621333 4633059 4987527 5937398 6064168 6429812 6584377 5259064 5349646 5946041 4540211 4762261 5273296 5616917 5627440 5794621 6059092 6059092 6068201 6456728 6505098 6711469 5402050 5525883 5841258 6463356 4614504 5040626 5343397 5369346 5378969 5644204 5672924 5838130 5872893 6229552).pn. (700/245 700/246 700/251 700/253 700/260 700/261 or 318/568.1 318/568.12 318/568.16 318/568.17 318/568.2 or 901/1 901/9 901/46 or 180/8.1 180/8.6 180/65.1 or 701/23 or 320/116 320/120 or 446/376 446/384).ccls.	97
<input type="checkbox"/>	L4		10164

<input type="checkbox"/>	L3	6580969.pn.	2
<input type="checkbox"/>	L2	11/456454	2
<input type="checkbox"/>	L1	10/511608	1

END OF SEARCH HISTORY